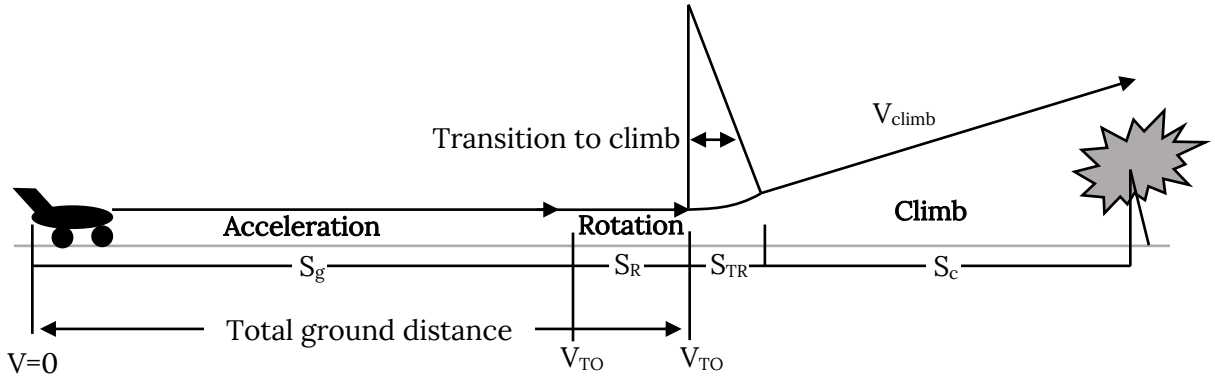
Transition to climb
V_{climb}
Acceleration
Rotation
Climb
S_g
S_R
S_{TR}
S_c
Total ground distance
V=0
V_{TO}
V_{TO}